FedPAGE: A Fast Local Stochastic Gradient Method for Communication-Efficient Federated Learning

Haoyu Zhao

Princeton University

haoyu@princeton.edu

Joint work with: Zhize Li and Peter Richtárik

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Figure: Zhize Li



Figure: Peter Richtárik

Overview



- 2 Problem Setting and Assumptions
- FedPAGE Algorithm

Convergence Results

- FedPAGE in the Nonconvex Setting
- FedPAGE in the Convex Setting

5 Proof Sketch

6 Numerical Experiments

Section 1

Introduction and Related Works

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General Problem Setting

- one central server and N clients
- each client holds M data (for simplicity)
- the clients can communicate with the central server but cannot connect with other clients
- there is a global model on the server, and the clients communicates with the server to update the model

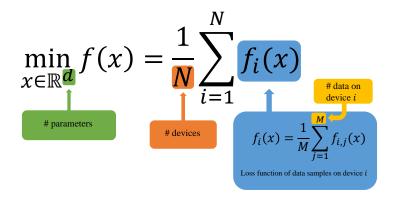


Figure: A federated learning application. The figure comes from the link.¹

¹https://blog.ml.cmu.edu/2019/11/12/federated-learning-challenges-methods-andfuture-directions/

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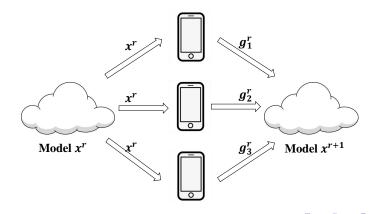
General Problem Setting

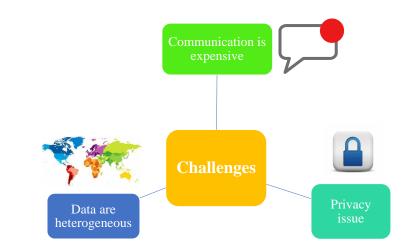


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General Problem Setting

- at each communication round r, the server broadcast the current model x^r to some clients S^r
- **2** the clients computes some function g_i^r and transfer back to the server
- **(a)** the server update the model according to g_i^r





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Challenges

- f 0 we do not transfer the data to the central server (privacy issue² \checkmark)
- We do not assume {f_i} or {f_{i,j}} to have similarity: we view them as arbitrary functions (heterogeneity issue (non IID issue) √)
- I how about the expensive communication (communication issue ?)



²Here transferring the gradient may also leak the personal information, but we do not consider this 'advanced' privacy in this project. Please refer to more differential privacy works for more information.

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There are two lines of work to overcome the communication problem: compression operators and local methods.

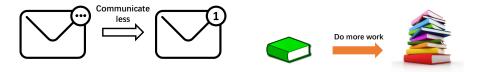


Figure: Compression operators: communicate less during one communication round

Figure: Local methods: work more during one communication round

Related Works — Compression Operators

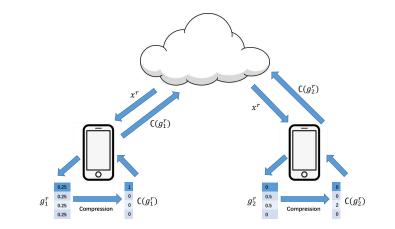


Figure: Compression operators: each device send the compressed information to the central server.

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- **QSGD** [Alistarh et al., 2017]: compressed version of SGD
- SignSGD [Bernstein et al., 2018]: compressed version of SGD
- OIANA [Mishchenko et al., 2019]: compressed version of SVRG
- ADIANA [Li et al., 2020]: accelerated version of DIANA

Related Works — Local Methods

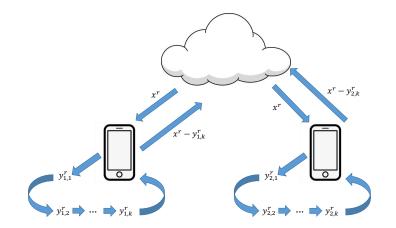


Figure: Local methods: each device perform multiple local updates before communicating with the central server.

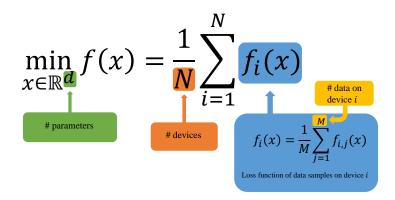
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- FedAvg [McMahan et al., 2017]: Stochastic gradient descent(SGD) with local steps
- Local-SVRG [Gorbunov et al., 2020]: SVRG[Johnson and Zhang, 2013] with local steps
- SCAFFOLD [Karimireddy et al., 2020]: SAGA[Defazio et al., 2014] with local steps
- FedPAGE (this paper): PAGE[Li et al., 2021] with local steps

Section 2

Problem Setting and Assumptions



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Nonconvex Setting:

- All functions can be nonconvex.
- **2** We want to find x such that $\mathbb{E} \|\nabla f(x)\| \leq \epsilon$.

Convex Setting:

- We assume f(x) is convex, and $f_i(x)$ may be nonconvex.
- **2** We want to find x such that $\mathbb{E}f(x) f^* \leq \epsilon$.

Assumption (L-smoothness)

All functions $f_{i,j} : \mathbb{R}^d \to \mathbb{R}$ for all $i \in [N], j \in [M]$ are L-smooth. That is, there exists $L \ge 0$ such that for all $x_1, x_2 \in \mathbb{R}^d$ and all $i \in [N], j \in [M]$,

$$\|\nabla f_{i,j}(x_1) - \nabla f_{i,j}(x_2)\| \leq L \|x_1 - x_2\|.$$

Can be generalized to different functions are $L_{i,j}$ smooth.

Assumption (Bounded Variance)

There exists $\sigma \geq 0$ such that for any client $i \in [N]$ and $x \in \mathbb{R}^d$,

$$\frac{1}{M}\sum_{j=1}^M \|\nabla f_{i,j}(x) - \nabla f_i(x)\|_2^2 \leq \sigma^2.$$

Section 3

FedPAGE Algorithm

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Algorithm 1 PAGE in the federated learning setting 1: for r = 1, 2, ..., R do sample $q \sim \text{Bernoulli}(p_r)$ 2: 3. if q = 1 then clients $S^r = [N]$, communicate x^r to all $i \in S^r$ 4: clients $i \in S^r$ compute $g_i^r \leftarrow \nabla f_i(x^r)$ 5: $g^r \leftarrow \frac{1}{|S^r|} \sum_{i \in S^r} g_i^r$ 6: 7: else clients $S^r \subseteq [N]$ with size S, send (x^r, x^{r-1}, g^{r-1}) to all $i \in S^r$ 8: clients $i \in S^r$ compute $g_i^r \leftarrow \nabla f_i(x^r) - \nabla f_i(x^{r-1}) + g^{r-1}$ 9: $g^r \leftarrow \frac{1}{|S^r|} \sum_{i \in S^r} g_i^r$ 10: end if 11: $x^{r+1} \leftarrow x^r - \eta_{\sigma} g^r$ 12: 13: end for

Algorithm 2 LocalSteps-Full

- 1: procedure LOCALSTEPS-FULL $(i, x^r, x^{r-1}, g^{r-1})$
- 2: $y_{i,0}^{r} \leftarrow x^{r}$ 3: $g_{i,0}^{r} \leftarrow \nabla f_{i}(x^{r}) - \nabla f_{i}(x^{r-1}) + g^{r-1}$ 4: $y_{i,1}^{r} \leftarrow y_{i,0}^{r} - \eta_{l}g_{i,0}^{r}$ 5: for k = 1, 2, ..., K - 1 do 6: $g_{i,k}^{r} \leftarrow \nabla f_{i}(y_{i,k}^{r}) - \nabla f_{i}(y_{i,k-1}^{r}) + g_{i,k-1}^{r}$ 7: $y_{i,k+1}^{r} \leftarrow y_{i,k}^{r} - \eta_{l}g_{i,k}^{r}$ 8: end for
- 9: $\Delta y_i^r \leftarrow x^r y_{i,K}^r$
- 10: **return** Δy_i^r
- 11: end procedure
 - We add local steps to PAGE when the server does not communicate with all clients (q = 0)

Algorithm 3 FedPAGE-Full		
1: for $r = 1, 2,, R$ do		
2: sample $q \sim \text{Bernoulli}(p_r)$		
3: if $q = 1$ then		
4: clients $S^r = [N]$, communicate x^r to all $i \in S^r$		
5: clients $i \in S^r$ compute $g_i^r \leftarrow \nabla f_i(x^r)$ and send to the server		
6: $g^r \leftarrow \frac{1}{ S^r } \sum_{i \in S^r} g_i^r$		
7: else		
8: clients $S^r \subseteq [N]$ with size S , send (x^r, x^{r-1}, g^{r-1}) to all $i \in S^r$		
9: $\Delta y_i^r \leftarrow \text{LOCALSTEPS-FULL}(i, x^r, x^{r-1}, g^{r-1})$		
10: $g^r \leftarrow \frac{1}{Km S^r } \sum_{i \in S^r} \Delta y_i^r$		
11: end if		
12: $x^{r+1} \leftarrow x^r - \eta_g g^r$		
13: end for		

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- FedPAGE-Full computes K local full gradients at each client when performing local steps, which is time consuming (procedure LOCALSTEPS-FULL)
- when *M* is very large, computing the local full gradient may not be affordable

Optimize the local steps: FedPAGE

Update rule in
LocalSteps-Full
$$g_{i,0}^{r} = \nabla f_{i}(x^{r}) - \nabla f_{i}(x^{r-1}) + g^{r-1}$$

$$g_{i,k+1}^{r} = g_{i,k}^{r} + \nabla f_{i}(y_{i,k+1}^{r}) - \nabla f_{i}(y_{i,k}^{r})$$

$$g_{i,0}^{r} = \nabla f_{i}(x^{r}) - \nabla f_{i}(x^{r-1}) + g^{r-1}$$

$$g_{i,k+1}^{r} = g_{i,k}^{r} + \nabla f_{i,j}(y_{i,k+1}^{r}) - \nabla f_{i,j}(y_{i,k}^{r})$$
Use a large batch
$$g_{i,0}^{r} = \nabla g_{i,k}^{r} + \nabla f_{i,j}(y_{i,k+1}^{r}) - \nabla f_{i,j}(y_{i,k}^{r})$$

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Optimize the local steps: FedPAGE

When M is very large and we cannot compute the local full gradient, we use large minibatch to estimate the local full gradient.

Algorithm 4 LocalSteps

- 1: procedure LOCALSTEPS $(i, x^r, x^{r-1}, g^{r-1})$ 2: $y_{i0}^r \leftarrow x^r$ $g_{i0}^r \leftarrow \nabla_{\mathcal{I}_2} f_i(x^r) - \nabla_{\mathcal{I}_2} f_i(x^{r-1}) + g^{r-1}$ 3: $y_{i1}^r \leftarrow y_{i0}^r - \eta_i g_{i0}^r$ 4: for k = 1, 2, ..., K - 1 do 5: sample $j \in [M]$, $g_{i,k}^r \leftarrow \nabla f_{i,j}(y_{i,k}^r) - \nabla f_{i,j}(y_{i,k-1}^r) + g_{i,k-1}^r$ 6: 7: $y_{i,k+1}^r \leftarrow y_{i,k}^r - \eta_l g_{i,k}^r$ 8: end for $\Delta y_i^r \leftarrow x^r - y_{i,K}^r$ 9: return Δy_i^r 10:
- 11: end procedure

Algorithm 5 FedPAGE		
	r r = 1, 2,, R do	
2:	sample $q \sim \text{Bernoulli}(p_r)$	
3:	if $q = 1$ then	
4:	clients $S^r = [N]$, communicate x^r to all $i \in S^r$	
5:	clients $i \in S^r$ compute $g_i^r \leftarrow \nabla_{\mathcal{I}_1} f_i(x^r)$ and send to the server	
6:	$g^r \leftarrow \frac{1}{ S^r } \sum_{i \in S^r} g_i^r$	
7:	else	
8:	clients $S^r \subseteq [N]$ with size S , send (x^r, x^{r-1}, g^{r-1}) to all $i \in S^r$	
9:	$\Delta y_i^r \leftarrow \text{LOCALSTEPS}(i, x^r, x^{r-1}, g^{r-1})$	
10:	$g^r \leftarrow \frac{1}{K_{n} S^r } \sum_{i \in S^r} \Delta y_i^r$	
11:	end if	
12:	$x^{r+1} \leftarrow x^r - \eta_g g^r$	
13: end for		

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Section 4

Convergence Results

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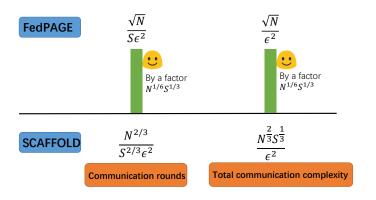
Theorem (Convergence of FedPAGE in nonconvex setting)

Under standard assumptions, if we choose the parameters properly, FedPAGE will find a point x such that $\mathbb{E} \|\nabla f(x)\|_2 \leq \epsilon$ within the following number of communication rounds:

$$R = O\left(\frac{L(\sqrt{N}+S)}{S\epsilon^2}\right).$$

- The number of communication round is $O(\sqrt{N}/(S\epsilon^2))$ when $S \le \sqrt{N}$, which matches the convergence rate of PAGE
- **②** The total communication complexity is $O(N + \sqrt{N}/\epsilon^2)$, because we communicate with all the clients in the first round

Convergence in the Nonconvex Setting



SCAFFOLD[Karimireddy et al., 2020]: State-of-the-art, ICML 2020

FedPAGE is more suitable when N is very large, e.g. federated learning applications related to mobile phones or PCs.

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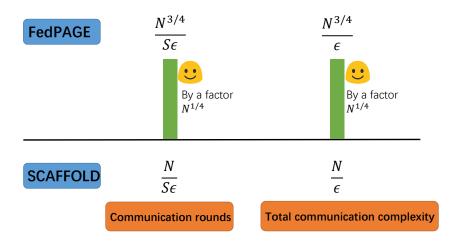
Theorem (Convergence of FedPAGE in convex setting)

Under standard assumptions, if we choose the parameters properly, FedPAGE will find a point x such that $\mathbb{E}f(x) - f^* \leq \epsilon$ with the number of communication rounds bounded by

$$R = O\left(\frac{N^{3/4}L}{S\epsilon}\right)$$

The number of communication round is O(N^{3/4}/(Sε)) when S ≤ √N
 The total communication complexity is O(N + N^{3/4}/ε), because we communicate with all the clients in the first round

Convergence in the Convex Setting



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Section 5

Proof Sketch

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- The main part is to bound the 'variance term'. We bound $\mathbb{E} \|g^r \nabla f(x^r)\|^2$
- **2** It is easy to bound $\mathbb{E} \| \frac{1}{5} \sum_{i \in S^r} g_{i,0}^r \nabla f(x^r) \|^2$ (main lemma in PAGE)

3 Bound
$$\mathbb{E} \| \frac{1}{S} \sum_{i \in S^r} g_{i,0}^r - g^r \|^2$$

- **3** Bound $\frac{1}{K} \sum_{k=0}^{K-1} \mathbb{E}_r ||g_{i,k}^r g_{i,0}^r||^2$, for any *i*, *k*, *r*
- If η_l is small, then $y_{i,k}^r ≈ x^r$, $g_{i,k}^r ≈ g_{i,0}^r$, and the above equation will be small

- PAGE/FedPAGE uses biased gradient estimator, need to bound the following inner product term.
- **2** We can bound the inner product $\sum_{r=1}^{t} \mathbb{E} \langle \nabla f(x^r) g^r, x^r x^* \rangle$
- For FedPAGE, we still need to consider the 'local error' generated from the local steps.
- Use the bounds on $\frac{1}{K} \sum_{k=0}^{K-1} \mathbb{E}_r ||g_{i,k}^r g_{i,0}^r||^2$, for any i, k, r

Section 6

Numerical Experiments

Image: A matrix

- We set the objectives to be robust linear regression and logistic regression with nonconvex regularizer
- 2 The objective function for robust linear regression is $f(x) = \frac{1}{n} \sum_{i=1}^{n} \ell(x^T a_i b_i)$, where $\ell(t) = \log(1 + \frac{t^2}{2})$
- The objective function for logistic regression with nonconvex regularizer is $f(x) = \frac{1}{n} \sum_{i=1}^{n} \log (1 + \exp(-b_i x^T a_i)) + \alpha \sum_{j=1}^{d} \frac{x_j^2}{1 + x_j^2}$
- We perform two experiments: the first shows the effectiveness of local steps, and the second compares FedPAGE with other methods.

Effectiveness of Local Steps

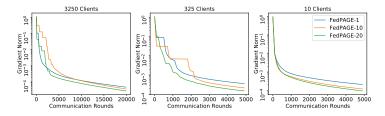


Figure: Robust linear regression on a9a dataset

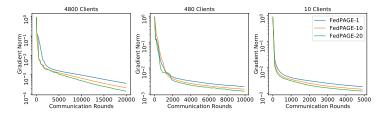


Figure: Robust linear regression on w8a dataset

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Superiority over Other Methods

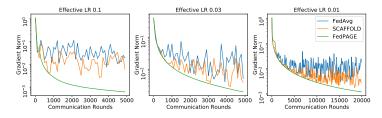


Figure: Robust linear regression on a9a with 3250 clients (each with 10 sample)

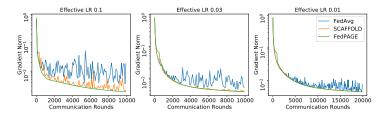


Figure: Robust linear regression on w8a with 4800 clients (each with 10 sample).

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Superiority over Other Methods

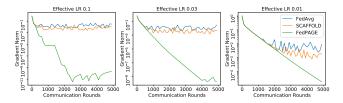


Figure: Logistic regression with nonconvex regularizer on a9a with 3250 clients (each with 10 sample)

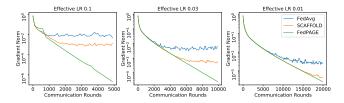


 Figure: Logistic regression with nonconvex regularizer on w8a with 4800 clients

 (each with 10 sample)

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- We design FedPAGE algorithm, which is a communication-efficient local method for federated learning.
- From theory, we improve the communication rounds and communication complexity of the state-of-the-art SCAFFOLD.
- From experiments, we show the effectiveness of local steps and superiority of FedPAGE over other existed methods.

Thanks

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